



Regularizing towards Causal Invariance: Linear Models with Proxies



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MIT



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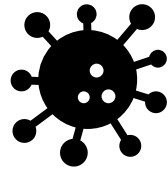


Jonas Peters
Univ. of
Copenhagen



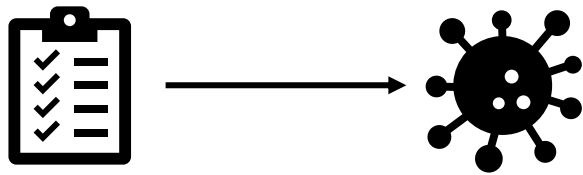
David Sontag
MIT

Motivation: Robustness to Dataset Shift



Y: Disease

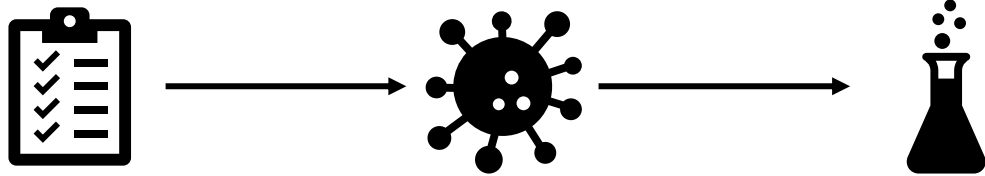
Motivation: Robustness to Dataset Shift



X_1 : Medical History

Y : Disease

Motivation: Robustness to Dataset Shift



X_1 : Medical History

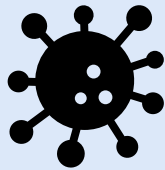
Y : Disease

X_2 : Lab Result

Motivation: Robustness to Dataset Shift



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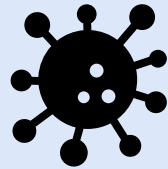
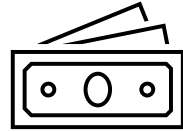


X_2 : Lab Result

Observed Distribution

Motivation: Robustness to Dataset Shift

A : Access to healthcare
(Unobserved)



X_1 : Medical History

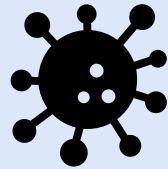
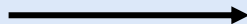
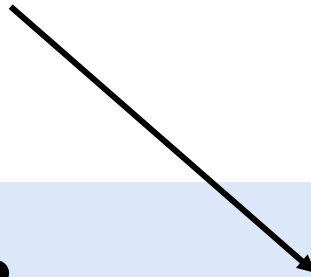
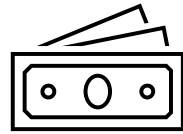
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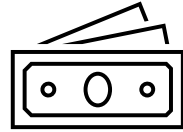
Example: Variation in access to regular high-quality testing.

Observed Distribution

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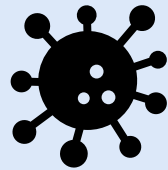
Challenge: Predictive performance may change due to changes in unobserved factors (e.g., economic shocks).



Example: Variation in access to regular high-quality testing.



X_1 : Medical History



Y : Disease



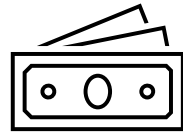
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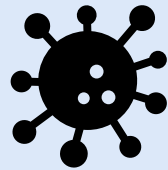
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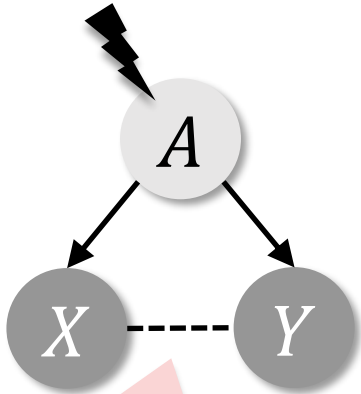
- 1 Protect against shift in unobserved factors?
- 2 Balance between accuracy & robustness?

Observed Distribution

Motivation: Robustness to Dataset Shift

Minimize worst-case loss over a set of interventions

Interventions on A change the distribution of $P(X, Y)$



Unknown causal graph between X, Y

$$\min \sup_{v \in C} E_{do(A:=v)} [(Y - \gamma^\top X)^2]$$

Assumptions

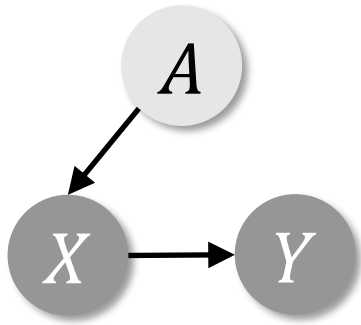
Linear structural causal model (SCM) over all observed and unobserved variables, and one or more **noisy proxies of A**

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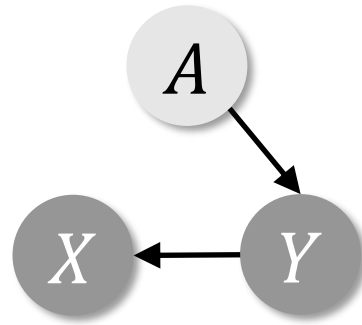
Linear structural causal model (SCM) over all observed and unobserved variables, and one or more **noisy proxies of A**

Any causal graph over X, Y, H is permitted, but A is an “anchor” with no causal parents.

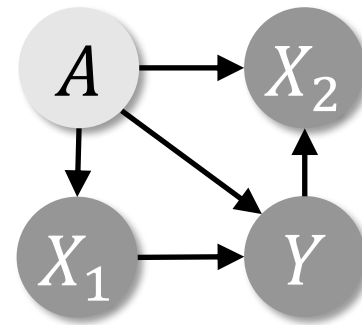
$$\begin{pmatrix} X \\ Y \\ H \end{pmatrix} := B \begin{pmatrix} X \\ Y \\ H \end{pmatrix} + M_A A + \epsilon$$



Covariate Shift



Label Shift



...and more

Assumptions

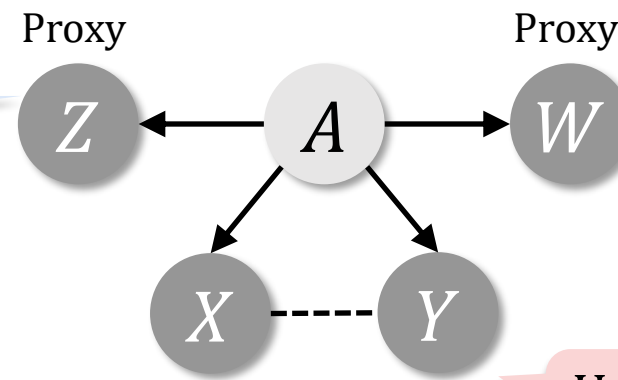
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Proxies are linear functions of A with independent additive noise.

Example: Self-reported data on income, distance to closest clinic, etc.



Unknown causal graph between X, Y

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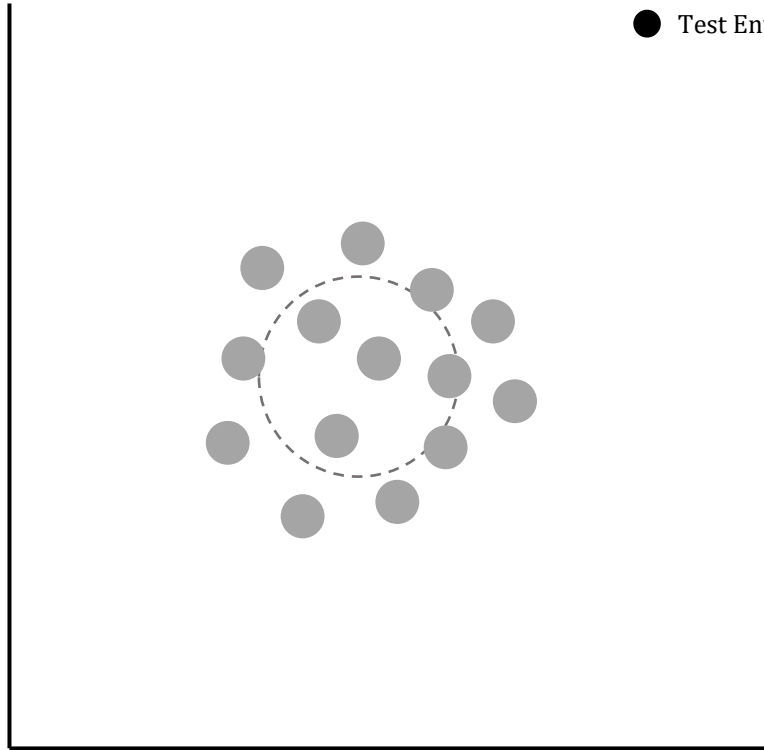
Using prior knowledge:

- 1 Specify **relevant factors of variation** A via proxies.
- 2 Specify **plausible shifts** via robustness set C .

Robustness to bounded interventions on A

A_1 : Access to
Primary Care

- Training Dist.
- Training Covariance
- Test Environment

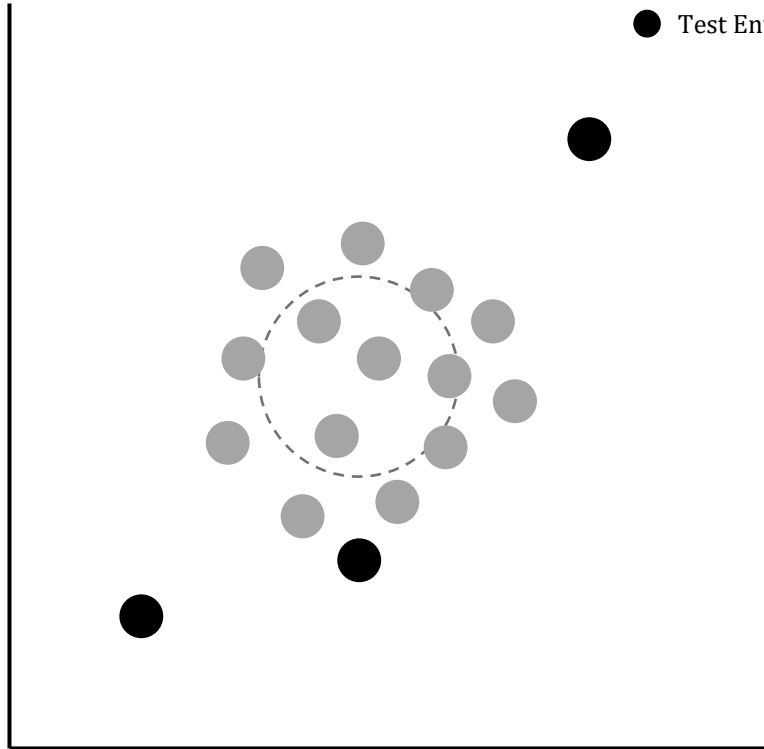


A_2 : Housing Stability

X, Y not shown here, just the
dimensions of A

Robustness to bounded interventions on A

A_1 : Access to
Primary Care



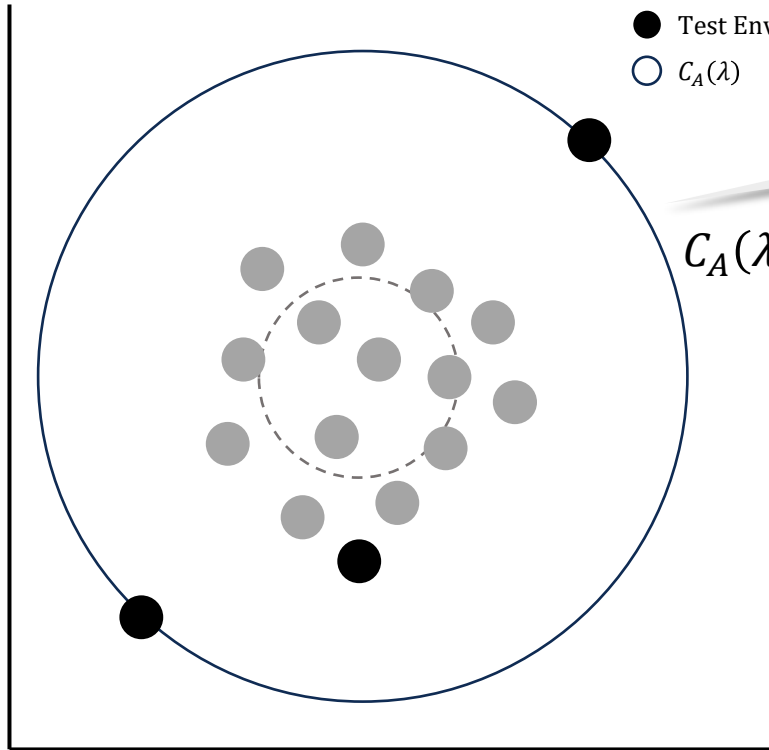
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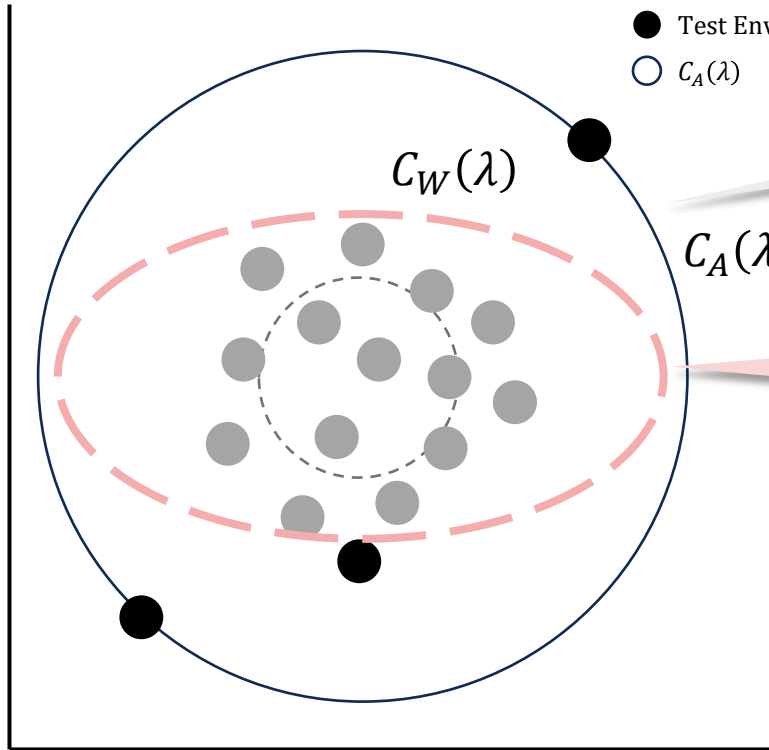
Anchor Regression [1] assumes that A is observed, and optimizes a worst-case loss over bounded interventions

$$\sup_{v \in C_A(\lambda)} E_{do(A := v)} [(Y - \gamma^T X)^2]$$

X, Y not shown here, just the dimensions of A

Robustness to bounded interventions on A

A_1 : Access to Primary Care



- Training Dist.
- Training Covariance
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- $C_A(\lambda)$

Anchor Regression [1] assumes that A is observed, and optimizes a worst-case loss over bounded interventions

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Theorem 1 (Informal)
 Given a single noisy proxy W of A , the robustness set is provably reduced, and this reduction is not identifiable.

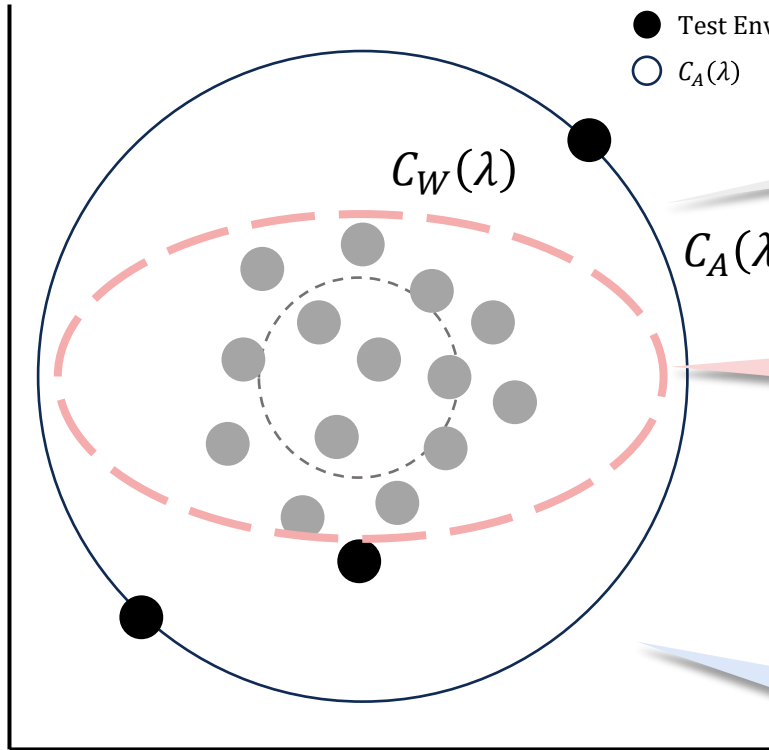
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[1] Rothenhäusler, D., Meinshausen, N., Bühlmann, P., and Peters, J. Anchor regression: Heterogeneous data meet causality. Journal of the Royal Statistical Society: Series B (Statistical Methodology), 83(2):215–246, 2021.

Robustness to bounded interventions on A

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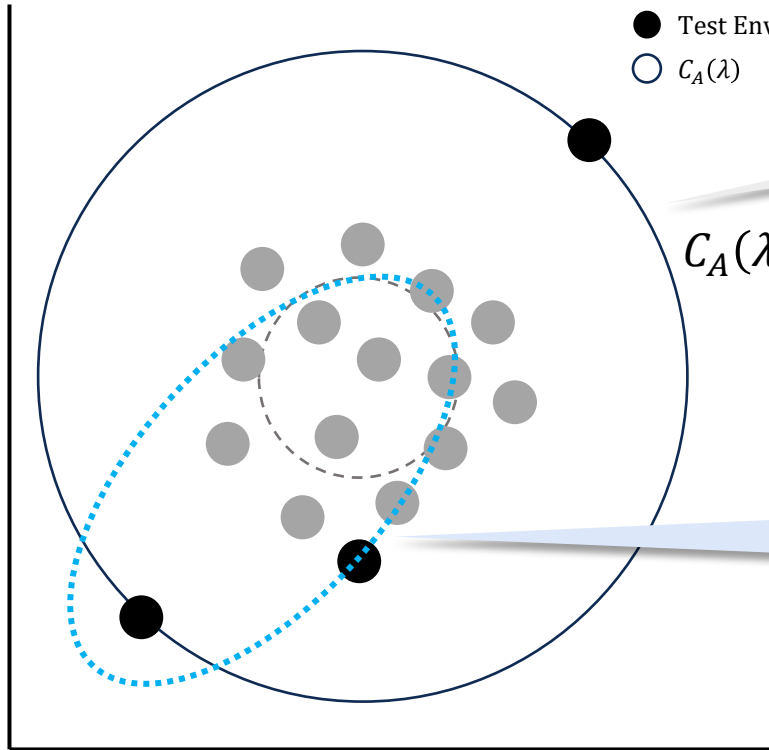
Theorem 1 (Informal)
 Given a single noisy proxy W of A , the robustness set is provably reduced, and this reduction is not identifiable.

Theorem 2 (Informal)
 Given two noisy proxies of A , one can recover the original robustness set, using a modified objective

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Targeting the robustness set with prior knowledge

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Theorem 3 (Informal)
We generalize to a larger class of robustness sets, and prove that the objective is identified with two proxies

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Conclusion

Incorporate **prior knowledge about future shifts**, instead of seeking invariance to arbitrary changes

- 1 Specify **relevant factors of variation A** via proxies
- 2 Specify **plausible shifts** via targeted robustness sets